组会汇报

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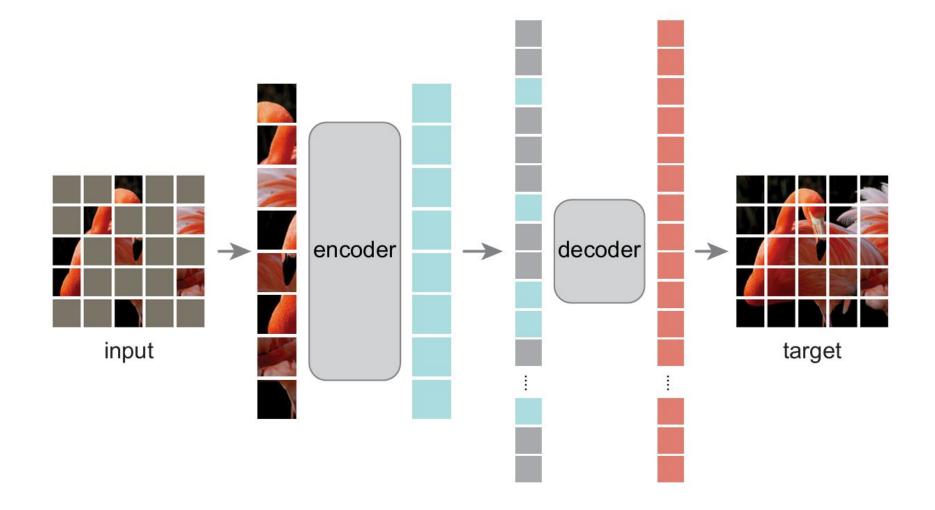
文献

Masked Autoencoders Are Scalable Vision Learners

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Abstract

This paper shows that masked autoencoders (MAE) are scalable self-supervised learners for computer vision. Our MAE approach is simple: we mask random patches of the input image and reconstruct the missing pixels. It is based on two core designs. First, we develop an asymmetric encoder-decoder architecture, with an encoder that operates only on the visible subset of patches (without mask tokens), along with a lightweight decoder that reconstructs the original image from the latent representation and mask tokens. Second, we find that masking a high proportion of the input image, e.g., 75%, yields a nontrivial and meaningful self-supervisory task. Coupling these two designs enables us to train large models efficiently and effectively: we accelerate training (by 3× or more) and improve accuracy. Our scalable approach allows for learning high-capacity models that generalize well: e.g., a vanilla ViT-Huge model achieves the best accuracy (87.8%) among methods that use only ImageNet-1K data. Transfer performance in downstream tasks outperforms supervised pretraining and shows promising scaling behavior



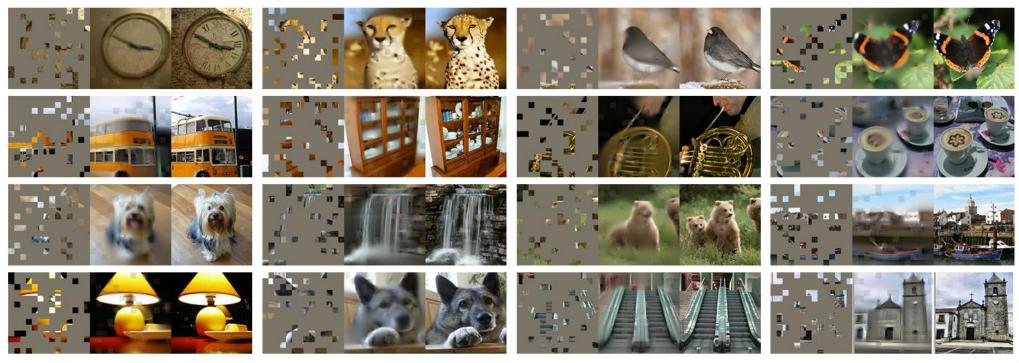


Figure 2. Example results on ImageNet *validation* images. For each triplet, we show the masked image (left), our MAE reconstruction[†] (middle), and the ground-truth (right). The masking ratio is 80%, leaving only 39 out of 196 patches. More examples are in the appendix. [†] As no loss is computed on visible patches, the model output on visible patches is qualitatively worse. One can simply overlay the output with the visible patches to improve visual quality. We intentionally opt not to do this, so we can more comprehensively demonstrate the method's behavior.



Figure 3. Example results on COCO validation images, using an MAE trained on ImageNet (the same model weights as in Figure 2). Observe the reconstructions on the two right-most examples, which, although different from the ground truth, are semantically plausible.

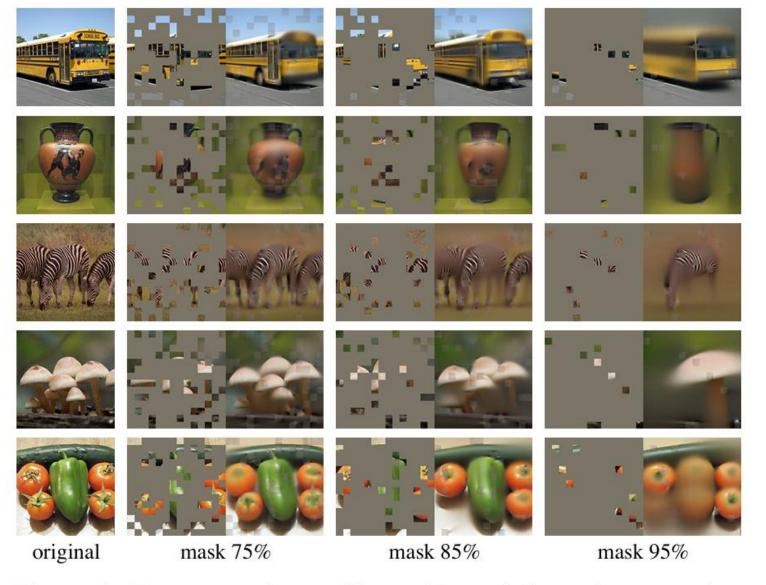


Figure 4. Reconstructions of ImageNet *validation* images using an MAE pre-trained with a masking ratio of 75% but applied on inputs with higher masking ratios. The predictions differ plausibly from the original images, showing that the method can generalize.

Experiments

We do self-supervised pre-training on the ImageNet-1K (IN1K) [13] training set. Then we do supervised training to evaluate the representations with (i) end-to-end fine-tuning or (ii) linear probing. We report top-1 validation accuracy of a single 224 224 crop.

blocks	ft	lin
1	84.8	65.5
2	84.9	70.0
4	84.9	71.9
8	84.9	73.5
12	84.4	73.3

(a) Decoder depth.	A	deep	decoder	can	im-
prove linear probing	acc	curacy	<i>t</i> .		

case	ft	lin
pixel (w/o norm)	84.9	73.5
pixel (w/ norm)	85.4	73.9
PCA	84.6	72.3
dVAE token	85.3	71.6

⁽d) **Reconstruction target**. Pixels as reconstruction targets are effective.

dim	ft	lin
128	84.9	69.1
256	84.8	71.3
512	84.9	73.5
768	84.4	73.1
1024	84.3	73.1

(b) **Decoder width**. The decoder can be narrower than the encoder (1024-d).

case	ft	lin	
none	84.0	65.7	
crop, fixed size	84.7	73.1	
crop, rand size	84.9	73.5	
crop + color jit	84.3	71.9	

(e) **Data augmentation**. Our MAE works with minimal or no augmentation.

case	ft	lin	FLOPs
encoder w/ [M]	84.2	59.6	3.3×
encoder w/o [M]	84.9	73.5	$1 \times$

(c) **Mask token**. An encoder without mask tokens is more accurate and faster (Table 2).

case	ratio	ft	lin
random	75	84.9	73.5
block	50	83.9	72.3
block	75	82.8	63.9
grid	75	84.0	66.0

(f) **Mask sampling**. Random sampling works the best. See Figure 6 for visualizations.

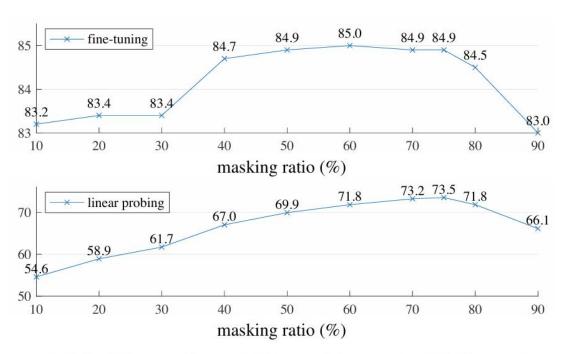


Figure 5. **Masking ratio**. A high masking ratio (75%) works well for both fine-tuning (top) and linear probing (bottom). The y-axes are ImageNet-1K validation accuracy (%) in all plots in this paper.

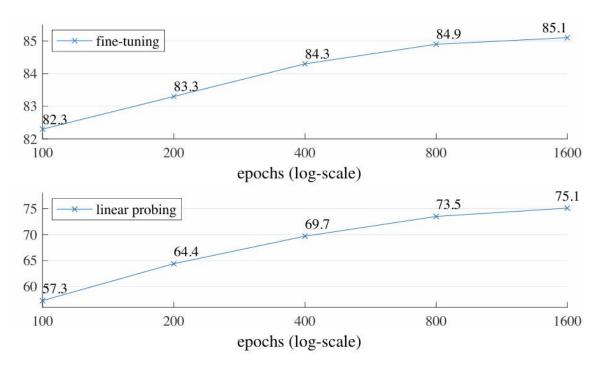


Figure 7. **Training schedules**. A longer training schedule gives a noticeable improvement. Here each point is a full training schedule. The model is ViT-L with the default setting in Table 1.

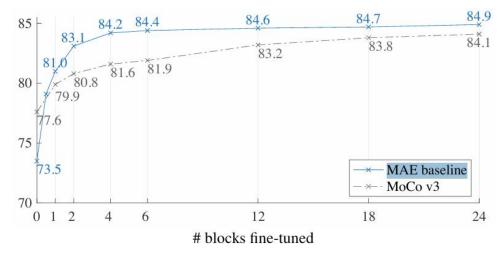


Figure 9. **Partial fine-tuning** results of ViT-L w.r.t. the number of fine-tuned Transformer blocks under the default settings from Table 1. Tuning 0 blocks is linear probing; 24 is full fine-tuning. Our MAE representations are less linearly separable, but are consistently better than MoCo v3 if one or more blocks are tuned.

method	pre-train data	ViT-B	ViT-L	ViT-H	ViT-H ₄₄₈
scratch, our impl.	<i>5</i> .	82.3	82.6	83.1	-
DINO [5]	IN1K	82.8	-	-	=
MoCo v3 [9]	IN1K	83.2	84.1	-	==
BEiT [2]	IN1K+DALLE	83.2	85.2	-	*:
MAE	IN1K	83.6	85.9	86.9	87.8

Table 3. Comparisons with previous results on ImageNet-1K. The pre-training data is the ImageNet-1K training set (except the tokenizer in BEiT was pre-trained on 250M DALLE data [50]). All self-supervised methods are evaluated by end-to-end fine-tuning. The ViT models are B/16, L/16, H/14 [16]. The best for each column is underlined. All results are on an image size of 224, except for ViT-H with an extra result on 448. Here our MAE reconstructs normalized pixels and is pre-trained for 1600 epochs.

Contribution

- **简单高效的自监督预训练方法:** 提出了掩码自编码器(*MAE*),一种通过随机遮蔽输入 图像并重建缺失像素的简单自监督方法。
- **创新的不对称架构设计:** 设计了只在编码器中处理未遮蔽图像块的编码器-解码器架构, 从而大幅减少计算量, 并通过轻量级解码器完成图像重构。
- **高比例遮蔽策略:** 发现采用高达 75% 的遮蔽比例可以形成一个非平凡的自监督任务,既促进了训练效率,也提升了模型性能。
- **优异的扩展性和泛化能力:** 实验结果证明, **MAE** 在仅使用 **ImageNet-1K** 数据的情况下即可训练出高容量、泛化良好的模型,并在多个下游任务(如目标检测、语义分割和图像分类)中超过了传统的监督预训练方法。

Thanks